TOWARDS OPERATIONAL AIRBORNE REMOTE SENSING OF WATER QUALITY IN THE NETHERLANDS

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ABSTRACT

Optical imaging techniques can be used to produce maps of concentrations of chlorophyll-*a*, total suspended matter and coloured dissolved organic carbon. The Rijkswaterstaat sets up a production chain for such maps using a hyperspectral imaging scanner installed in the Dutch coast guard aircraft. Multiple use of aircraft and scanner makes data acquisition more cost effective. Water quality parameters are retrieved from remote sensing images using successively; 1) A module that calculates subsurface reflectance spectra, it corrects for atmospheric and air-water interface effects using MODTRAN embedded in TOOLKIT. 2) A module that calculates concentrations of water constituents from the subsurface irradiance reflectance spectra and specific inherent optical properties using matrix inversion. Specific inherent optical properties of the water constituents are not necessarily simultaneous measured to the airborne measurements. Effects of instrumental noise, errors in the atmospheric correction and errors in the specific inherent optical properties on the derived concentrations of water constituents were estimated.

An image was taken from Lake Veluwe in The Netherlands with complementary *in situ* measurements, including reflectance spectra and specific absorption and back scattering spectra of water constituents and concentrations of water constituents. The data were used to validate the system by 1) forward modelling of the reflectance spectra based on the Gordon model using a set of measured specific inherent optical properties, concentrations of the constituents and measured reflectance spectra, 2) comparison of the atmospheric corrected airborne measurements and reflectance spectra measured from a ship, and 3) comparison of the measured concentrations with the calculated concentrations.

1. INTRODUCTION

Tabel 1. Notification						
Symbol	description	Units		Symbol	description	Units
а	total absorption coefficient	m ⁻¹		L_{wu}	subsurface upward radiance	W m ⁻² nm ⁻¹ sr ⁻¹
a^*_{CDOM}	absorption coefficient of CDOM	m ⁻¹		L _{rs,b}	average background radiance seen by	$W m^{-2} nm^{-1} sr^{-1}$
a_{CHL}^{*}	specific absorption coefficient of CHL	$m^2 mg^{-1}$			detector	
a_{TSM}^*	specific absorption coefficient of TSM	$m^2 g^{-1}$		$L_{rs,t}$	total upward radiance detected by	$W m^{-2} nm^{-1} sr^{-1}$
aw.	absorption coefficient of pure water	m ⁻¹			sensor	2 1 1
b_b	total back scattering coefficient	m ⁻¹		L_{sky}	downward sky radiance at 42° zenith	$W m^{-2} nm^{-1} sr^{-1}$
$b_{h TSM}^*$	specific back scattering coefficient of	$m^2 g^{-1}$		-	angle	
0,100	TSM	U		Q	conversion coefficient for L_{wu} to E_{wu}	-
$b_{b,w}$	back scattering coefficient of pure	m ⁻¹		r_{sky}	Fresnel reflectance coefficient for	-
<i>,</i>	water				sunlight	
CHL	concentration of chlorophyll a	mg m ⁻³		<i>r_{dif}</i>	Freshel reflectance coefficient for	-
E_{ad}	downward irradiance above water	W m ⁻² nm ⁻¹			airruse light	
	surface			r_{Θ}	Freshel reflectance coefficient for	-
E_{wu}	subsurface upward irradiance	W m ⁻² nm ⁻¹		$\mathbf{D}(0^{-})$	sunight	
f	conversion coefficient for L_{au} to L_{wu}	-		R(0)	subsurface irradiance reflectance	-
F	fraction diffuse light of E_{ad}	-		K(0)	above surface radiance reflectance	3
Lau	upward radiance above water surface	W m ⁻² nm ⁻¹ sr ⁻¹		ISM	concentration of 1SM	g m -

Water managers have a request for maps of water quality parameters such as concentrations of chlorophyll-*a* (*CHL*), total suspended matter (*TSM*) and coloured dissolved organic matter (*CDOM*). Currently they rely on local point measurements made from buoys or ships, the traditional monitoring techniques for coastal or inland waters. Optical imaging techniques could supply the water managers with maps of the parameters of interest making use of the information enclosed in spectra of reflected light measured above the water surface. These imaging techniques have progressed rapidly but application retarded. Implementation of the airborne remote sensing of water quality parameters was obstructed by its relative high costs and low flexibility. Also the need of ground truth to be measured in parallel to

the airborne measurements was considered as a disadvantage. Currently Rijkswaterstaat is setting up a chain for production of water quality maps using airborne imaging remote sensing where these drawbacks mentioned have been taken away.

An imaging hyperspectral scanner (EPS-A) recently was installed in the Dutch coast guard aircraft. Multiple use of this aircraft makes exploitation of the imaging scanner more cost effective. Due to the flexibility of the coast guard aircraft it is expected that acquisition of data is easier to organise. The third drawback is removed by implementation of a matrix inversion technique to estimate concentrations of the water constituents using reflectance spectra and specific inherent optical properties (SIOP)for input. This procedure does not rely on simultaneous ground truth measurements to the airborne measurements. The procedure is explained in more detail below.

Demands on the accuracy of the production chain, user requirements for the accuracy of the concentrations of the water quality parameters, were set by the data users by interviewing several people responsible for water management in The Netherlands (van der Woerd *et al* 1998). How realistic these user requirements are remains a topic of discussion. The requirements can be summarised as follows: 10% accuracy in the chlorophyll-a pigment concentration for coastal and inland water and 10% and 25% for the total suspended matter concentration for coastal waters and inland water respectively. No clear user requirements were obtained for the dissolved organic carbon concentration. The feasibility of these user requirements with the set up production chain was studied An error analysis of the matrix inversion technique was performed where errors in the atmospheric correction procedure, errors in the SIOP, errors in the radiometric calibration and the signal to noise ratio of the detector were counted for.

The production chain was tested with a case study on the Lake Veluwe in The Netherlands. Hyperspectral images were and in situ measurements were acquired under optimal atmospheric conditions. The complementary *in situ* measurements were taken at 9 stations, including reflectance spectra and specific absorption and back scattering spectra of the water constituents and concentration of the water. The data were use to validate the system by

- a) forward modelling of the reflectance spectra based on the Gordon model using a set of measured SIOP, concentrations of the constituents and measured reflectance spectra,
- b) comparison of the atmospheric corrected airborne measurements and reflectance spectra measured from a ship
- c) comparison of the measured concentrations with the calculated concentrations.

2. THEORY

The retrieval of water quality parameters from hyperspectral remote sensing images is a based on the following chain of modules;

- 1. acquisition of the airborne hyperspectral images followed by radiometric calibration and geometric correction. Thus images are obtained with data on spectral upward radiance. Radiometric calibration and geometric correction is not discussed in this paper.
- 2. calculation of $R(0^{\circ})$ from the upward radiance spectra by correction for incident light intensity, atmospheric influences and effects introduced by the air-water interface. The module uses the radiative transfer program MODTRAN embedded in TOOLKIT (de Haan *et al* 1999).
- 3. calculation of concentrations of the water constituents using matrix inversion technique. The specific inherent absorption and scattering coefficients of the water constituents and R(0⁻) are needed for input. Measurements of the SIOP are not necessarily performed simultaneously to the airborne measurements.

Water quality parameters are derived using matrix inversion on a pixel by pixel basis. This system is currently in a preoperational phase.

2.1 Calculation of R(0⁻) from airborne measurements

The images were corrected for atmospheric influences using TOOLKIT (de Haan *et al* 1999). Briefly the correction procedure performs calculation of $R(0^+_{app})$ and $R(0^-)$ respectively with

$$R(0_{app}^{+}) = \frac{c_1 + c_2 \cdot L_{rs,t} + c_3 \cdot L_{rs,b}}{c_4 + c_5 \cdot L_{rs,b}}$$
 Eq. 1

where $c_1 c_2 c_3 c_4$ and c_5 are atmospheric correction parameters and

$$R(0^{-}) = \frac{d_1 + d_2 \cdot R(0^+_{app})}{d_3 + d_4 \cdot R(0^+_{app})}$$
 Eq. 2

where $d_1 d_2 d_3$ and d_4 are the interface correction parameters. Details on the TOOLKIT and atmospheric correction procedure used can be found in de Haan *et al* (1999). The $R(0^-)$ obtained here should match to the $R(0^-)$ obtained from the Gordon model described below using actual SIOP and concentrations of water constituents. The wavelength dependence is omitted for simplicity.

2.2 Inverse modelling

The $R(0^{-})$ can also be calculated by the simple reflectance model suggested by Gordon (1975) which is given by:

$$R(0^{-}) = f \cdot \frac{b_b}{a + b_b}$$
 Eq. 3

The constant f is chosen to be 0.33 but may vary due to solar and viewing geometry. The model assumes an optically deep medium so that bottom effects can be ignored. Also stratification in the water column and inelastic scattering effects, such a Raman scattering and fluorescence are ignored. The absorption and backscattering coefficients of the natural water can be expressed in terms of the constituent of the water, as follows:

$$a = a_w + a_{CHL}^* \cdot CHL + a_{TSM}^* \cdot TSM + a_{CDOM}^* \cdot CDOM$$
 Eq. 4

$$b_b = b_{b,w} + b_{b,TSM}^* \cdot TSM$$
 Eq. 5

No scattering for CDOM and chlorophyll-a is assumed. Substitution of equations 4 and 5 into equation 3 yields

$$R(0^{-}) = f \cdot \frac{b_{b,w} + b_{b,TSM}^{*} \cdot TSM}{a_{w} + b_{b,w} + a_{CHL}^{*} \cdot CHL + (a_{TSM}^{*} + b_{b,TSM}^{*}) \cdot TSM + a_{CDOM}^{*} \cdot CDOM}$$
Eq. 6

This equation provides an explicit relationship between the SIOP, the concentrations of the water constituents and $R(0^{-})$. To determine the concentrations from $R(0^{-})$ the equation is rewritten as a linear system of equations: Ax = b with

$$A = \left(\frac{R(0^{-})}{f} \cdot a_{CHL}^{*}\right|_{\lambda=1.n} \frac{R(0^{-})}{f} \cdot [a_{TSM}^{*} + b_{b,TSM}^{*}] - b_{b,TSM}^{*}\right|_{\lambda=1.n} \frac{R(0^{-})}{f} \cdot a_{CDOM}^{*}\right|_{\lambda=1.n}$$
Eq. 7
$$b = \left(-\frac{R(0^{-})}{f}[a_{w} + b_{bw}] + b_{bw}\right|_{\lambda=1.n}$$
and
$$x = \begin{pmatrix} CHL \\ TSM \\ CDOM \end{pmatrix}$$
Eq. 9

Thus, to estimate the unknown concentrations the linear equations can be solved with a least square approach using $A^T \cdot A \cdot x = A^T \cdot b$ where A^T is the transpose of A. This can be done if observations of $R(0^-)$ are available at minimal 3 wavelengths, the SIOP are known and a fixed value for f is chosen (e.g. 0.33).

3. MEASUREMENTS

Images of spectral upward radiance were measured of Lake Veluwe at May 26 and 27 1999, around 11:30h GMT using a hyperspectral imaging spectrometer (EPS-A) mounted into the Dutch coast guard aircraft flying at 3000m altitude. Pixels size of about 10x10m² were obtained. To reduce instrumental noise of the EPS-A an averaging 9 pixels each time was performed. Ground truth measurements were performed at May 26, 1999. Due to better optimal meteorological conditions during the second day, no clouds and very little cirrus, this image was used for further processing and comparison to the *in situ* measurements. Ground truth measurements consisted of determination of reflectance spectra (all stations), SIOP (6 stations) and concentrations of the water constituents (all stations). For comparison of the data sets the concentrations of the water constituents in the Lake Veluwe were assumed constant over time.

The $R(0^{\circ})$ spectra were measured according to the method of Gons (1999) using equation:

$$R(0^{-}) = \frac{Q \cdot f \cdot (L_{au} - r_{sky} \cdot L_{sky})}{(E_{ad} - r_{\Theta}(1 - F) \cdot E_{ad} - r_{dif} \cdot F \cdot E_{ad}) + 0.5 \cdot E_{wu}}$$
Eq. 10

The measured parameters are L_{au} , L_{sky} and E_{ad} . The coefficient Q varied between 2.9 and 4.7 depending on solar angle and the ratio between total and diffuse downward light. The value of r_{sky} was 0.0293, f = 1.82 for fresh water, $r_{dj}=0.06$ (Jerlov 1976), r_{Θ} was calculated from Julian day, daytime and geographical position and F was obtained from shading off measurements.

Absorption spectra of the sum of total suspended matter and algae pigments were measured using the filterpad method (Trüper and Yentch 1967) with a 0.45 µm Whatman GF/F filters. The absorption of total suspended matter was obtained after extraction of the pigments from the filter according to method of Kishino et al (1985). Residual scatter was corrected for by subtraction of the value at 750nm for the whole spectrum. The absorption spectra of algae pigments were obtain by subtraction of the spectra. The absorption spectra of coloured dissolved organic matter were measured from water filtered over 0.45 µm filters. The concentrations of total suspended matter were measured from the dried filters. Concentrations of algae pigments were measured from ethanol extracted pigments. Beam attenuation spectra were measured from unprocessed samples. The scattering coefficient of the total suspended matter was calculated from the difference between the total absorption spectrum and the beam attenuation spectrum. The backscattering to scattering ratio spectrum was estimated to be 0.027,

4. RESULTS

4.1 Match between R(0⁻) spectra obtained with different methods.

The subsurface irradiance reflectance spectra were determined for one station with the three different techniques mention above. A good correspondence between the spectra can be seen in Figure 2. The correspondence between the modelled and the ship based measured reflectance spectra was optimised was optimised with the scattering to backscattering ratio. This way the specific backscattering coefficient was obtained. The correspondence between the ship based and the modelled reflectance validates the optical model used in the Matrix Inversion Method. The correspondence between the ship based and the airborne measured reflectance spectra validates the atmospheric correction procedure. The airborne spectra show high spectral noise in comparison with the other spectra which is due to the instrumental noise of the EPS-A. Recently the signal to noise ratio of the EPS-A has been improved by factor 6.



Figure 2. Reflectance spectra ship based and airborne measurements and model calculations.

4.2 Validity of matrix inversion method

Estimation of the concentrations of the water constituent from the $R(0^{-})$ with the use of matrix inversion techniques is affected by errors due to instrumental noise, errors due to the atmospheric correction procedure and errors in the SIOP. Different techniques for inversion of the matrix were tested on modelled reflectance spectra. It appeared that the least square method leads to the most erroneous results. The errors were reduced by a spectral weighting of the reflectance

based on an optimised fit between the ship based measured $R(0^{-})$ and modelled $R(0^{-})$, see Figure 2.



Figure 1. SIOP of the water constituents in the Lake Veluwe and optical properties of pure water according to Pope and Fry (1997) modified by Hakvoort and Doerffer in the near infrared part of the spectrum.

data in the matrix inversion. The best results were obtained with the Levenberg Marquardt method. A more detailed report of these findings will be published separately. For this study the least squares method was used. In case of a normal distribution of noise in the SIOP its effect on the derived concentrations appeared to be of minor effect. A normally distributed noise in the $R(0^{-})$ appeared to have its major effect in the estimation of the chlorophyll concentration. Figure 3 shows the effect of the additive noise in the SIOP and $R(0^{-})$.



Figure 3. Concentrations of the water constituents as derived from reflectance spectra with a 20 percent noise in SIOP and a 5 percent noise in the $R(0^{-})$. The concentrations were obtained with matrix inversion based on a least square fit.



Figure 4. Same notation as for Figure 3 but with an additional of 0.5 percent bias to the $R(0^{-})$. Note the differences in the Y-axes when compared to Figure 3, especially for CHL and DOC.

A spectral shift may occur due to an erroneous atmospheric correction, spectral effects being stronger in the blue wavelength range is for this example ignored. In case the reflectance spectra are shifted by 0.5 percent difficulties occur in obtaining the concentration of chlorophyll and CDOM. The concentration of TSM is overestimated with the matrix inversion but remains within the required accuracy. The chlorophyll-*a* concentration is out of the required accuracy. Difficulties in obtaining the CDOM concentration can be seen from Figure 4c. Negative values are obtain due to the spectral shift. This problem is to be solved in near future. For now the problem can be get around by adapting a fixed value for the CDOM concentration. This way the accuracy of the estimated concentrations of the other constituents is improved



Figure 5. Total suspended matter concentration obtained using matrix inversion. (1 <50g m⁻³)



Figure 6 Concentration of chlorophyll a obtained using matrix inversion. (1 ≤ 50 g m⁻³) The black colour means that no accurate data were obtained from matrix inversion.

4.3 Case study

The matrix inversion technique was applied on an hyperspectral airborne image. A fixed value for the CDOM concentration was used to circumvent the problem described above. The *in situ* measurements showed the CDOM concentration constant over the lake. The concentration of TSM and CHL obtained are shown in Figure 5 and 6 respectively. Ground truth concentrations are listed in Table 2. A close resemblance was found between the remote sensing data and the in situ data for TSM. The red colour in the lower part of the TSM image is not a high TSM concentration but is due to sunglint. No effort was made to distinguish sun glint. This will be done in the near future.

 Tabel 2. Concentrations of the water constituents

 measured *in situ*

Station	$TSM (g m^{-3})$	$CHL (mg m^{-3})$
V2	8.4	9.5
V3	7.4	9.6
V4	6.0	8.3
V5	8.8	10.6
V6	6.9	8.8
V7	8.5	8.0
V8	8.0	7.7
V9	43.2	8.6
V10	11.3	6.4

For the chlorophyll image large areas are black. These areas have been flagged due to negative values of the chlorophyll concentrations caused by a low signal to noise ratio of the EPS-A. Currently the EPS-A has been upgraded and results are expected to be not flagged of anymore. The high values for chlorophyll are caused by water plants. No effort was made yet to distinguish for water plants. The striping in figure 6 is due to the mirrors of the scanners not being 100 percent equal. Correction for this effect was omitted in this study.

5. CONCLUSION

The production chain of maps of water quality parameters has been defined. First results of a test on the chain using an imperfect airborne scanner show promising results. Improvement of the signal to noise ratio will improve the results especially those for chlorophyll a. Improvement can also be obtained be using the Levenberg Marquardt method with the matrix inversion. More study is needed to obtain accurate CDOM concentrations from the reflectance spectra. Near future experiences with the production chain has to demonstrate the robustness of the system as a monitoring tools for water quality parameters. More work on validation of the system has to be done

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