3D semantic labelling of colored LiDAR point cloud using supervoxels based segmentation approach.

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Methodology

Steps:

1) Integration of digital aerial images(ortho photos) with the LiDAR point cloud data to produce a coloured point cloud.
2) Supervoxels based segmentation was used to segment the point cloud data resulting in 3D segments.
3) Spectral and geometrical features are extracted from the 3D segments created.
4) The features are classified using machine learning algorithms into 6 classes.
5) The feature labels were transferred to the points within the each segment.